Cep telefonunuzu gözetmene teslim ediniz / Deposit your cell phones to invigilatorApril 25, 2019 [4:00 pm-5:10 pm]Math 216/ Second ExamPage 1 of 4

Math 216/ Second Exam			
THE NO. OF THE PARTY OF THE PAR			
Your Signature / İm	za		
Your Department / I	Bölüm		
		$\langle \rangle$	
• In order to receive credit, you must show all of your work . If you do not indicate the way in which you solved a problem, you may get little or no credit for it, even if your answer is correct. Show your work in evaluating any limits, derivatives .		Points	Score
		25	
question.	2	18	
er sheet. Please make sure	3	32	1
	4	25	
	T (1	100	
	Math 216/ Second Exam Your Signature / İm Your Department / İm Your Department / Im all of your work. If you be a problem, you may get yer is correct. Show your es. question. er sheet. Please make sure	Math 216/ Second Exam Your Signature / İmza Your Department / Bölüm all of your work. If you a problem, you may get yer is correct. Show your es. question. question. all of your work. If you a problem, you may get yer is correct. Show your es. question. 1 2 3 4	Math 216/ Second Exam Your Signature / İmza Your Department / Bölüm Your Department / Bölüm all of your work. If you at a problem, you may get yer is correct. Show your es. question. er sheet. Please make sure Yer is correct. Y

1. 25 Points Solve the Initial Value Problem

$$y'' + 4y = f(t) = \begin{cases} t, & 0 \le t < 3, \\ 1, & 3 \le t < \infty; \end{cases} \quad y(0) = 0, \ y'(0) = 0$$

Solution: The function f can be written as $f(t) = t - t\mathcal{U}(t-3) + \mathcal{U}(t-3)$, so by linearity, we have

$$\begin{aligned} \mathscr{L}\{y''\} + 4\mathscr{L}\{y\} &= \mathscr{L}\{t - (t - 3)\mathscr{U}(t - 3) - 2\mathscr{U}(t - 3)\} \\ s^2 Y(s) - sy(0) - y'(0) + 4Y(s) &= \frac{1}{s^2} - \frac{1}{s^2}e^{-3s} - \frac{3}{s}e^{-3s} + \frac{1}{s}e^{-3s} \\ (s^2 + 4)Y(s) &= \frac{1}{s^2} - \left(\frac{2}{s} + \frac{1}{s^2}\right)e^{-3s} \\ Y(s) &= \frac{1}{s^2(s^2 + 4)} - \left(\frac{2s + 1}{s^2(s^2 + 4)}\right)e^{-3s} \\ y(t) &= \mathscr{L}^{-1}\{Y(s)\} = \mathscr{L}^{-1}\left\{\frac{1}{s^2(s^2 + 4)}\right\} - \mathscr{L}^{-1}\left\{\left(\frac{2s + 1}{s^2(s^2 + 4)}\right)e^{-3s}\right\} \\ y(t) &= \boxed{\frac{1}{4}t - \frac{1}{8}\sin(2t) - \left(\frac{1}{4} - \frac{1}{4}(t - 3) - \frac{1}{4}\cos 2(t - 3) + \frac{1}{8}\sin 2(t - 3)\right)\mathscr{U}(t - 3)} \end{aligned}$$

where we have

$$\mathscr{L}^{-1}\left\{\frac{1}{s^2(s^2+4)}\right\} = \mathscr{L}^{-1}\left\{\frac{1}{4}\frac{1}{s^2} - \frac{1}{8}\frac{2}{s^2+4}\right\} = \frac{1}{4}t - \frac{1}{8}\sin(2t)$$

and

$$\mathscr{L}^{-1}\left\{\frac{2s+1}{s^2(s^2+4)}\right\} = \mathscr{L}^{-1}\left\{\frac{1}{4}\frac{1}{s} - \frac{1}{4}\frac{1}{s^2} - \frac{1}{4}\frac{s}{s^2+4} + \frac{1}{8}\frac{2}{s^2+4}\right\} = \frac{1}{4} - \frac{1}{4}t - \frac{1}{4}\cos(2t) + \frac{1}{8}\sin(2t)$$

p.695, pr.37

2. 18 Points Find the inverse Laplace transform of

$$F(s) = \frac{3s+3}{s^2+2s+5}.$$

Solution: Notice that the denominator $s^2 + 2s + 5$ is irreducible over the reals. Completing the square, $s^2 + 2s + 5 = (s+1)^2 + 4$. Now convert the function into a rational function of the variable u = s + 1. That is,

$$\frac{3s+3}{s^2+2s+5} = \frac{3(s+1)}{(s+1)^2+4}$$

We know that

$$\mathscr{L}^{-1}\left\{\frac{3u}{u^2+4}\right\} = 3\cos(2t).$$

Using the fact that $\mathscr{L}\left\{e^{at}f(t)\right\} = [\mathscr{L}\left\{f(t)\right\}]_{s \to s-a}$,

$$\mathscr{L}^{-1}\left\{\frac{3s+3}{s^2+2s+5}\right\} = 3e^{-t}\cos(2t).$$

p.491, pr.86

f(t)	$F(s) = \mathscr{L}[f](s)$	
1	$\frac{1}{s}$	<i>s</i> > 0
e ^{at}	$\frac{1}{s-a}$	s > a
t^n $(n \in \mathbb{N})$	$\frac{n!}{s^{n+1}}$	s > 0
sin at	$\frac{a}{s^2+a^2}$	s > 0
cos at	$\frac{s}{s^2+a^2}$	s > 0
sinh at	$\frac{a}{s^2-a^2}$	s > a
cosh at	$\frac{s}{s^2-a^2}$	s > a
$e^{at}\sin bt$	$\frac{b}{(s-a)^2+b^2}$	s > a
$e^{at}\cos bt$	$\frac{s-a}{(s-a)^2+b^2}$	s > a
$t^n e^{at}$ $(n \in \mathbb{N})$	$\frac{n!}{(s-a)^{n+1}}$	s > a
$u_c(t)$	$\frac{e^{-cs}}{s}$	s > 0
$u_c(t)f(t-c)$	$e^{-cs}F(s)$	
$e^{ct}f(t)$	F(s-c)	
f(ct) $(c > 0)$	$\frac{1}{c}F\left(\frac{s}{c}\right)$	
$\int_0^t f(t-\tau)g(\tau)d\tau$	F(s)G(s)	
$t^n f(t)$	$(-1)^n F^{(n)}(s)$	

3. Find the *inverse Laplace transform* of

$$F(s) = \frac{1}{(s+1)(s-2)}.$$

(a) 16 Points Using partial fractions.

Solution: We write

$$\begin{split} F(s) &= \frac{1}{(s+1)(s-2)} = \frac{A}{s+1} + \frac{B}{s-2} \\ 1 &= A(s-2) + B(s+1) \\ 1 &= As - 2A + Bs + B \Rightarrow 1 = (A+B)s - 2A + B \\ \Rightarrow A + B &= 0, \quad -2A + B = 1 \Rightarrow B = 1/3, A = -1/3 \\ &= \frac{1}{(s+1)(s-2)} = \frac{-1/3}{s+1} + \frac{1/3}{s-2} \\ \Rightarrow \mathscr{L}^{-1} \left\{ \frac{1}{(s+1)(s-2)} \right\} = \mathscr{L}^{-1} \left\{ \frac{-1/3}{s+1} \right\} + \mathscr{L}^{-1} \left\{ \frac{1/3}{s-2} \right\} = \boxed{\frac{1}{3} \left(e^{2t} - e^{-t} \right)} \end{split}$$

(b) 16 Points Using Convolution theorem.

Solution: Let
$$G(s) = \frac{1}{s+1}$$
 and $H(s) = \frac{1}{s-2}$ so that
 $g(t) = e^{-t}$ and $h(t) = e^{2t}$.
By the Convolution theorem,

$$f(t) = \mathscr{L}^{-1} \{F(s)\} = \mathscr{L}^{-1} \{G(s)H(s)\}$$

= $g * h = e^{-t} * e^{2t}$
= $\int_0^t e^{-\tau} e^{2(t-\tau)} d\tau = \int_0^t e^{2t-3\tau} \cos \tau d\tau = -\frac{1}{3} \left[e^{2t-3\tau} \right]_0^t = \overline{\frac{1}{3} \left(e^{2t} - e^{-t} \right)}$
583, pr.17

4. 25 Points Find the general solution of the system

$$\mathbf{x}' = \begin{bmatrix} -2 & 1\\ 1 & -2 \end{bmatrix} \mathbf{x}.$$

Solution: We first find the eigenvalues and eigenvectors of the matrix of coefficients. From the characteristic equation

$$\det(A - \lambda I) = \begin{vmatrix} -2 - \lambda & 1 \\ 1 & -2 - \lambda \end{vmatrix} = (-2 - \lambda)(-2 - \lambda) - (1)(1) = 4 + 4\lambda + \lambda^2 - 1 = \lambda^2 4\lambda + 3 = (\lambda + 3)(\lambda + 1) = 0$$

we see that the eigenvalues are $\lambda_1 = -3$ and $\lambda_2 = -1$.

Now for $\lambda_1 = -3$, $(A - \lambda_1 I)\mathbf{K} = 0$ is equivalent to

 $k_1 + k_2 = 0$ $k_1 + k_2 = 0.$

Thus $k_1 = -k_2$. When $k_2 = 1$ the related eigenvector is

$$\mathbf{K}_1 = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

For $\lambda_2 = -1$, we have

$$-k_1 + k_2 = 0$$

$$k_1 - k_2 = 0.$$

so $k_1 = k_2$ therefore with $k_2 = 1$ the corresponding eigenvector

$$\mathbf{K}_2 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

Since the matrix of coefficients A is a 2×2 matrix and since we have found two linearly independent solutions,

$$\mathbf{X}_1 = \begin{bmatrix} 1 \\ -1 \end{bmatrix} e^{-3t}$$
 and $\mathbf{X}_2 = \begin{bmatrix} 1 \\ 1 \end{bmatrix} e^{-t}$,

we conclude that the general solution of the system is

$$\mathbf{X} = c_1 \mathbf{X}_1 + c_2 \mathbf{X}_2 = c_1 \begin{bmatrix} 1 \\ -1 \end{bmatrix} e^{-3t} + c_2 \begin{bmatrix} 1 \\ 1 \end{bmatrix} e^{-t}$$

p.573, pr.38